

Multiresolution Point-set Surfaces

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GI 2008

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Outline

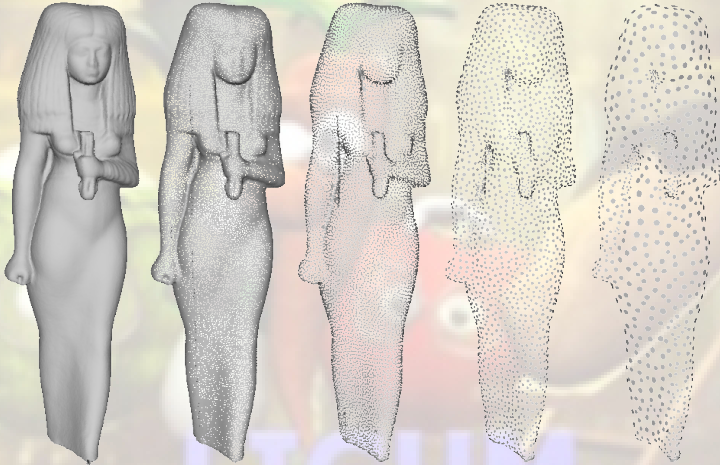
- 1 Introduction
- 2 Analysis
- 3 Synthesis
- 4 Results
- 5 Conclusion & Future Work

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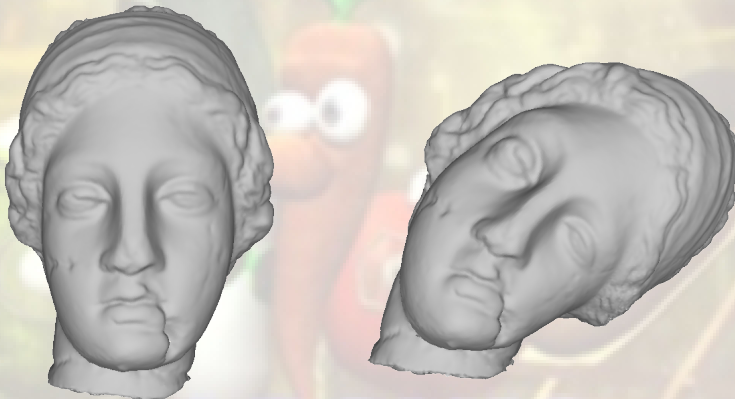
Point-set Surfaces and Surface Editing

- Point-set surfaces are becoming popular for shape modeling
- Surface editing in the presence of fine geometric details can be problematic
- Multiresolution representations for meshes are well known
- Interest for multiresolution representation for point-set surfaces

Decomposition



Surface Editing

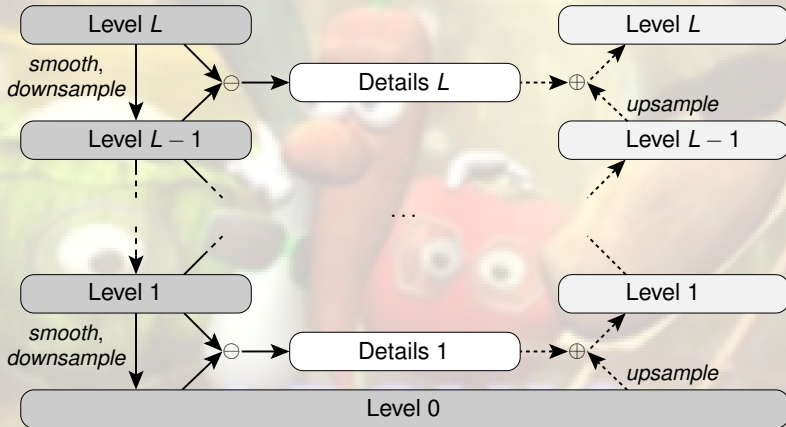


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Overview

Analysis

Synthesis



Previous Work

- Multiresolution meshes

[Eck+ 95] [Lounsbery+ 97] [Zorin+ 97] [Kobbelt+ 98]
[Guskov+ 99] [Lee+ 00] [Guskov+ 00]
[Hubeli-Gross 01] ...

- “Multiresolution” for points: mostly hierarchical structures geared for rendering

[Pfister+ 00] [Rusinkiewicz+ 00] [Botsch+ 02]
[Pajarola 03] [Park+ 04] [Pajarola+ 05] [Wu+ 05] ...

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Previous Work

- Progressive point-set surfaces
[Fleishman+ 03] [Singh-Narayanna 06]
- Triangle fans
[Linsen-Prautzsch 03]
- Multiscale point-set surfaces
[Pauly+ 06] [Zhang+ 05]

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Previous Work

- Progressive point-set surfaces
[Fleishman+ 03] [Singh-Narayanna 06]
- Triangle fans
[Linsen-Prautzsch 03]
- **Multiscale point-set surfaces**
[Pauly+ 06] [Zhang+ 05] + [Boubekeur+ 07]

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Outline

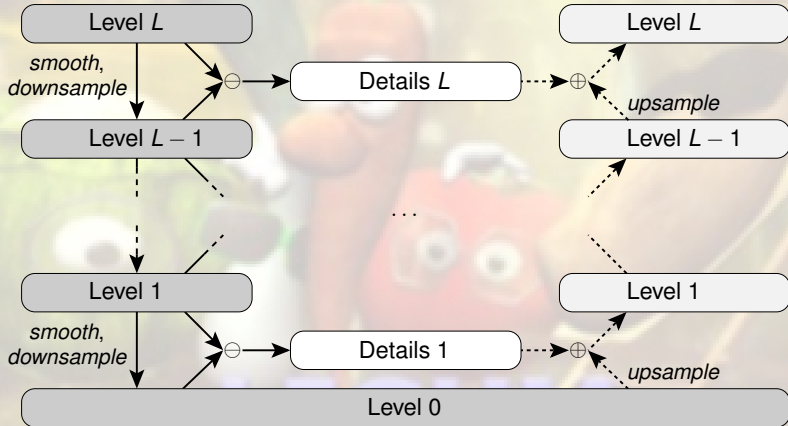
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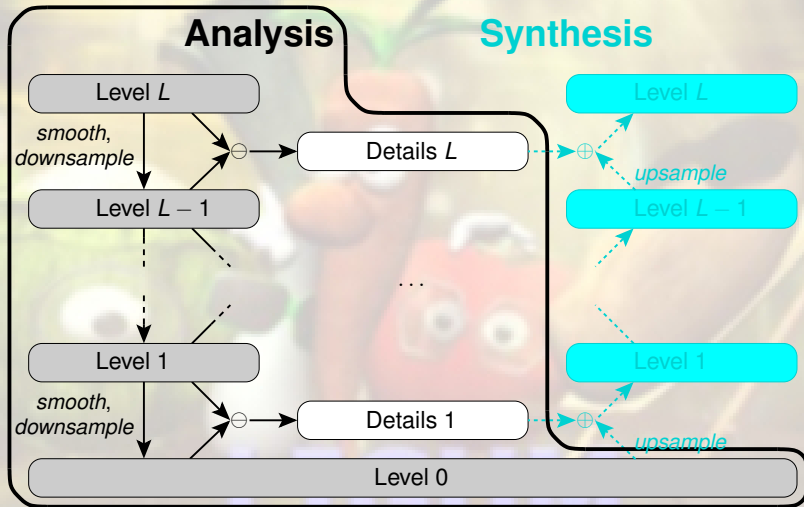
Analysis

Analysis

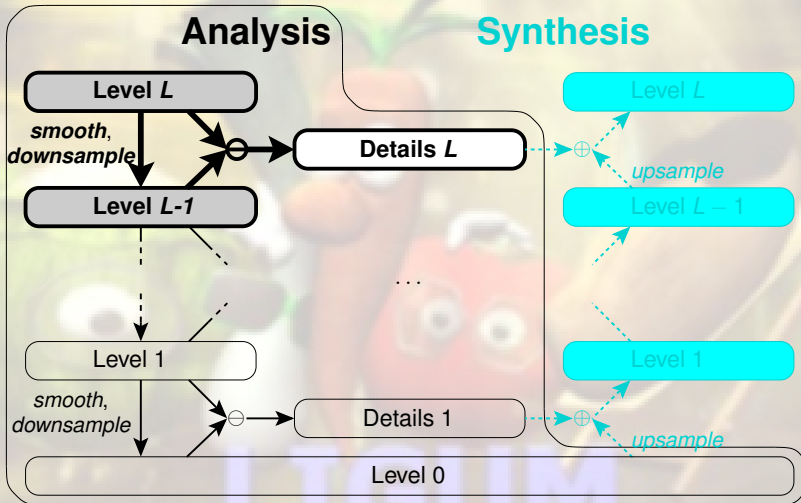
Synthesis



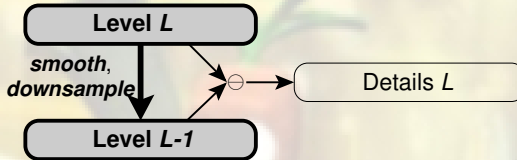
Analysis



Analysis

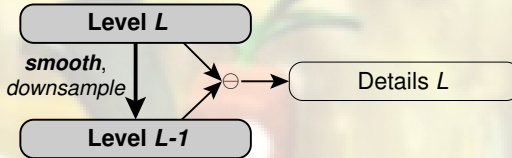


Coarser Level Generation



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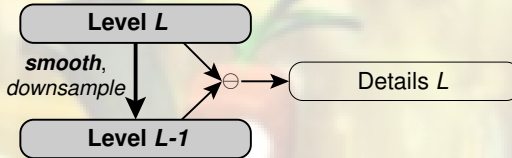
Coarser Level Generation



- MLS surfaces \Rightarrow smoothing by MLS projection

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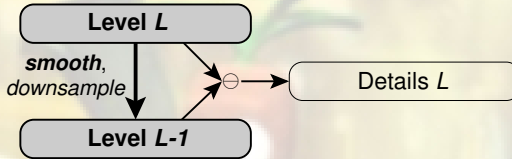
Coarser Level Generation



- MLS surfaces \Rightarrow smoothing by MLS projection
- Downsample point set before projection

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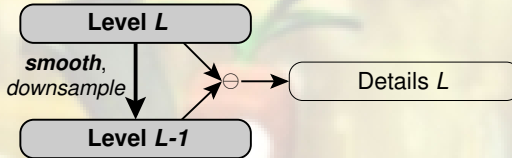
Coarser Level Generation



- MLS surfaces \Rightarrow smoothing by MLS projection
- Downsample point set before projection
- Similar to [Pauly+ 06], but constant downsampling factor

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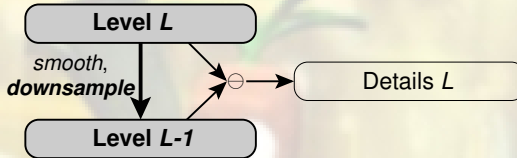
Coarser Level Generation



- MLS surfaces \Rightarrow smoothing by MLS projection
- **Downsample** point set before projection
- Similar to [Pauly+ 06], but constant **downsampling** factor

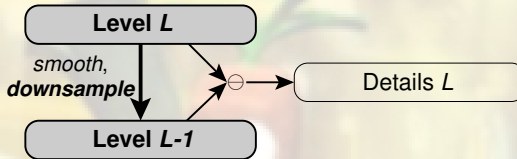
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Coarser Level Generation



- Downsampling: same as smoothing

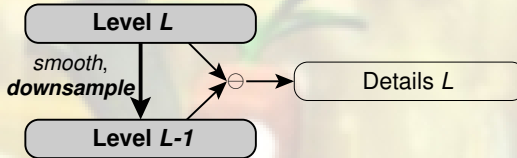
Coarser Level Generation




- Downsampling: same as smoothing
- However:



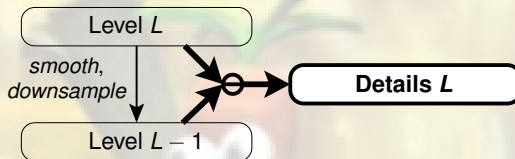
Coarser Level Generation



- Downsampling: same as smoothing
- However: 
- Add extra refinement step using heuristics based on k -neighborhood analysis

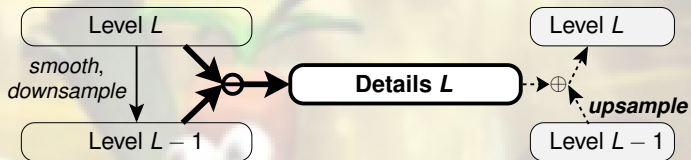
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Detail Extraction



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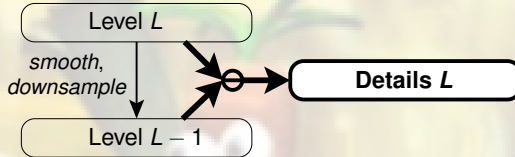
Detail Extraction



- Main difficulty: represent detail information coherently with upsampling procedure

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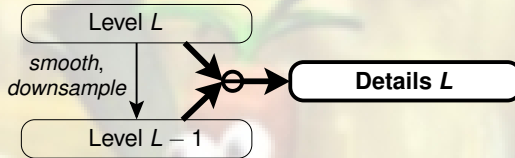
Detail Extraction



- Main difficulty: represent detail information coherently with upsampling procedure
- Meshes profit from explicit connectivity information

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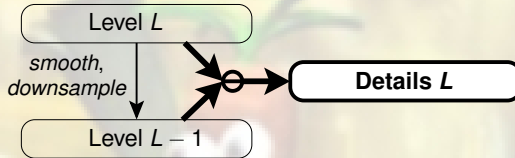
Detail Extraction



- Main difficulty: represent detail information coherently with upsampling procedure
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- [Linsen-Prautzsch 03]: store full k -neighborhood

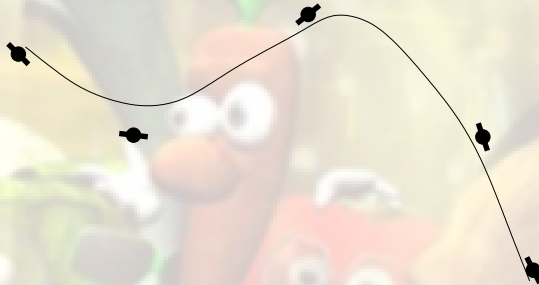
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Detail Extraction



- Main difficulty: represent detail information coherently with upsampling procedure
- Meshes profit from explicit connectivity information
- [Linsen-Prautzsch 03]: store full k -neighborhood
- Intrinsic reformulation [Boubekeur+ 07]

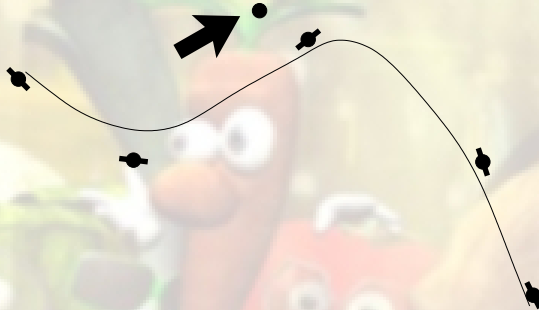
Extraction Procedure



Level $L - 1$

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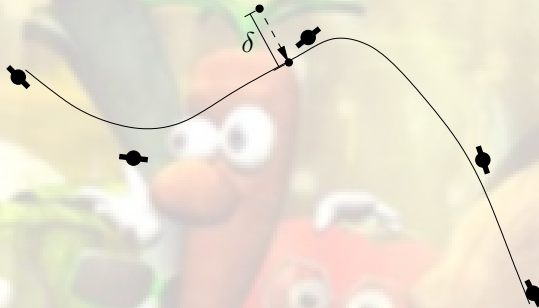
Extraction Procedure



Point from level L

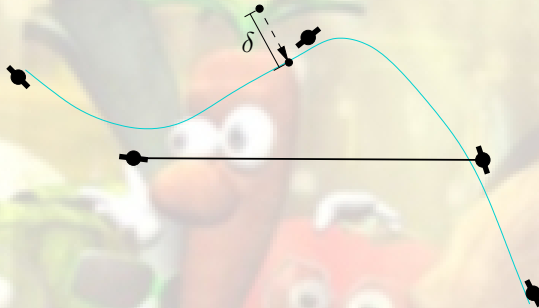
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Extraction Procedure



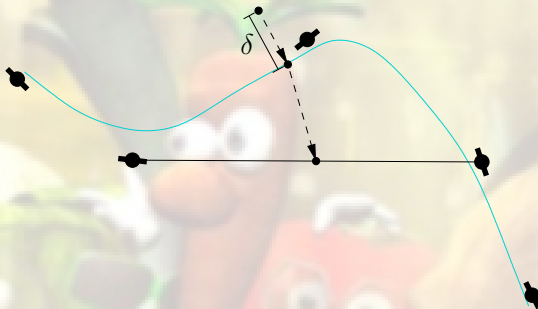
- 1 Project on level $L - 1$
 δ = geometric detail information

Extraction Procedure



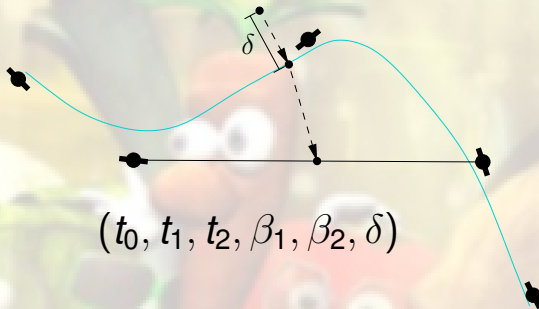
- 1 Project on level $L - 1$
- 2 Find a *surrounding* triangle

Extraction Procedure



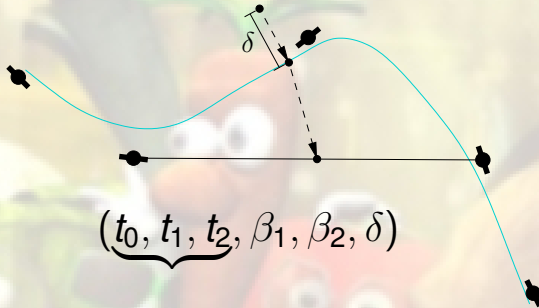
- 1 Project on level $L - 1$
- 2 Find a *surrounding* triangle
- 3 Reformulate projection relative to the triangle

Extraction Procedure



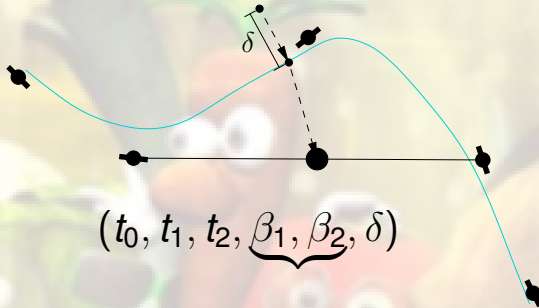
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Extraction Procedure



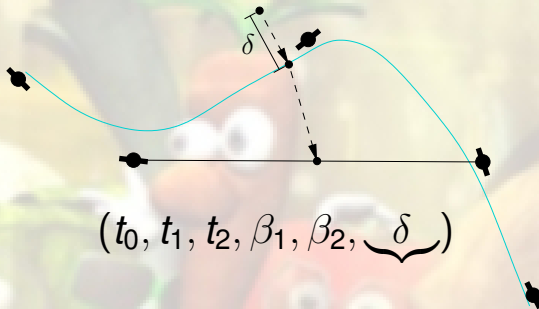
- ① Project on level $L - 1$
- ② Find a *surrounding* triangle
- ③ Reformulate projection relative to the triangle

Extraction Procedure



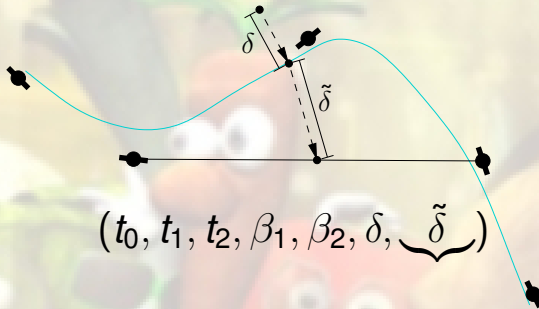
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Extraction Procedure



- ① Project on level $L - 1$
- ② Find a *surrounding* triangle
- ③ Reformulate projection relative to the triangle

Extraction Procedure



$$(t_0, t_1, t_2, \beta_1, \beta_2, \delta, \underbrace{\tilde{\delta}})$$

- ① Project on level $L - 1$
- ② Find a *surrounding* triangle
- ③ Reformulate projection relative to the triangle

Triangle selection



Triangle selection

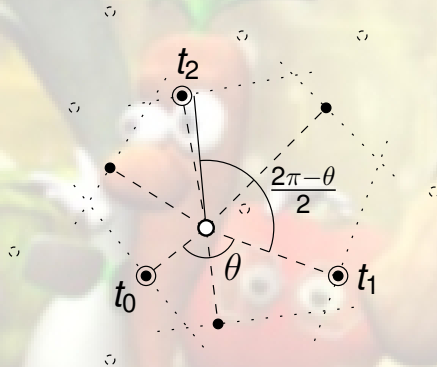


Triangle selection



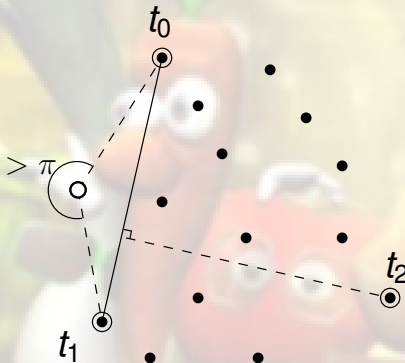
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Triangle selection



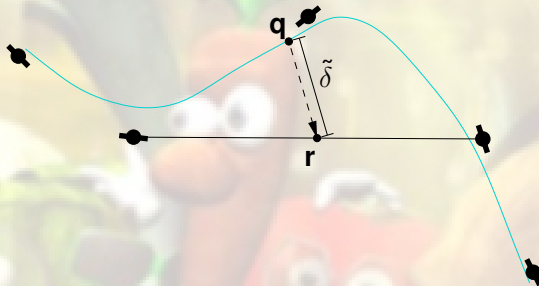
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Triangle selection



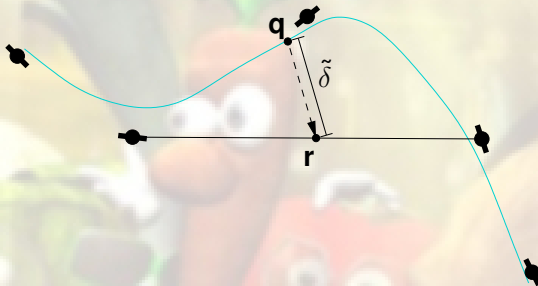
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Reformulation



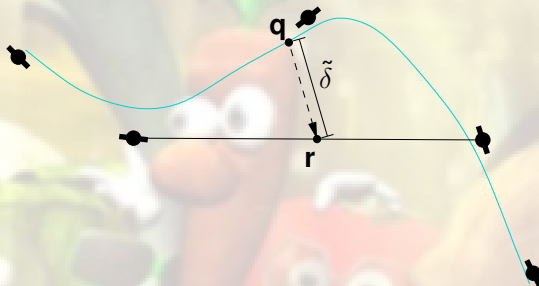
- Find a point \mathbf{r} on the triangle such that $\mathbf{q} = \mathbf{r} + \tilde{\delta}\mathbf{n}(\mathbf{r})$ for some $\tilde{\delta}$
($\mathbf{n}(\mathbf{r})$ = normal estimation at \mathbf{r})

Reformulation



- Find a point \mathbf{r} on the triangle such that $\mathbf{q} = \mathbf{r} + \tilde{\delta}\mathbf{n}(\mathbf{r})$ for some $\tilde{\delta}$
- Iterative procedure (gory details in the paper)

Reformulation



- Find a point \mathbf{r} on the triangle such that $\mathbf{q} = \mathbf{r} + \tilde{\delta}\mathbf{n}(\mathbf{r})$ for some $\tilde{\delta}$
- Iterative procedure
- β_1, β_2 computed from \mathbf{r}

Outline

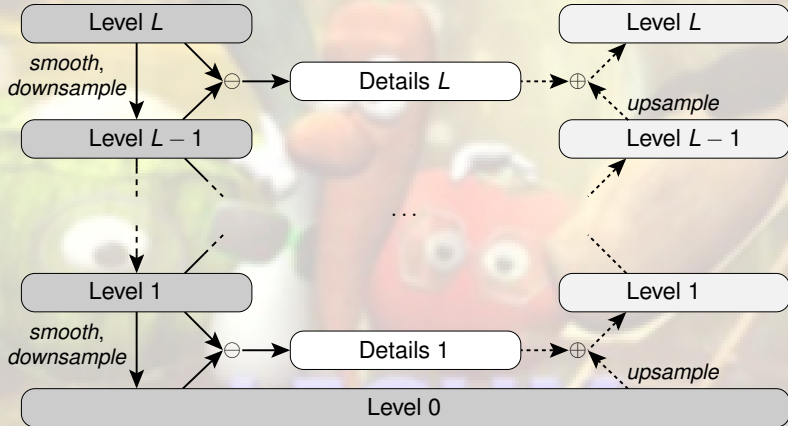
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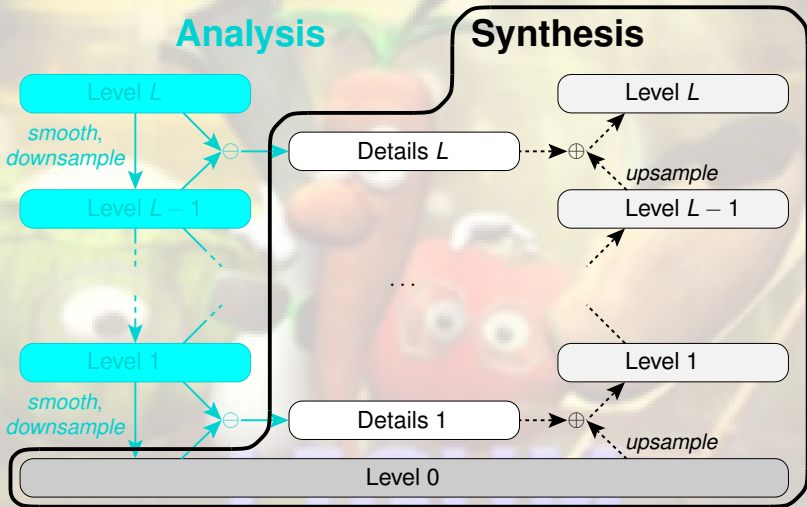
Synthesis

Analysis

Synthesis

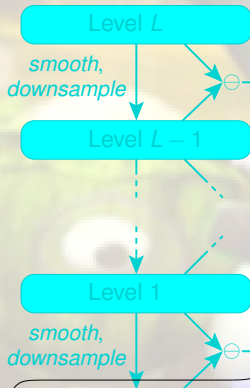


Synthesis

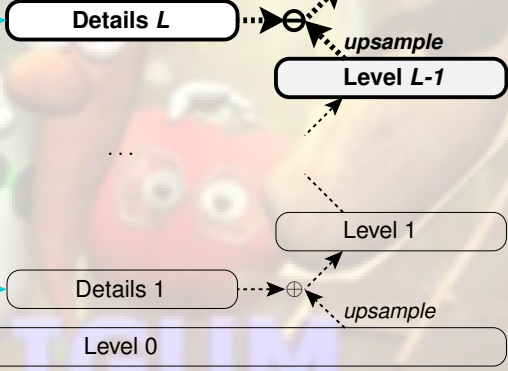


Synthesis

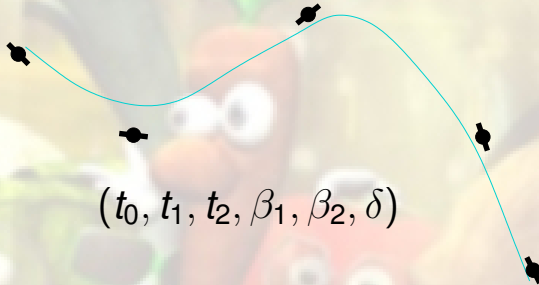
Analysis



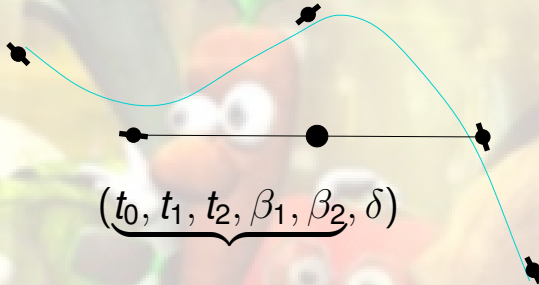
Synthesis



Synthesis Procedure



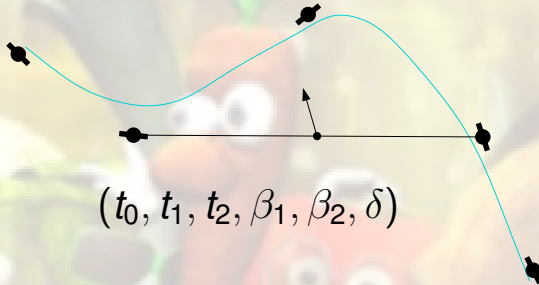
Synthesis Procedure



- 1 Compute base position

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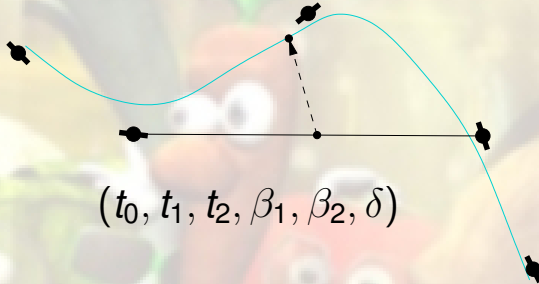
Synthesis Procedure



- 1 Compute base position
- 2 Estimate normal direction at base position

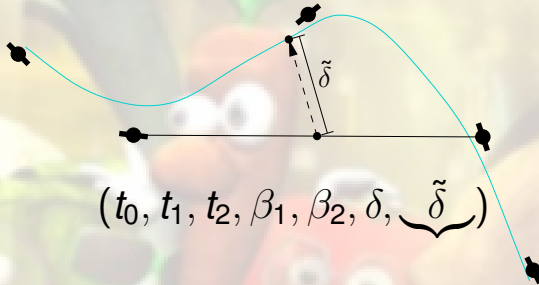
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Synthesis Procedure



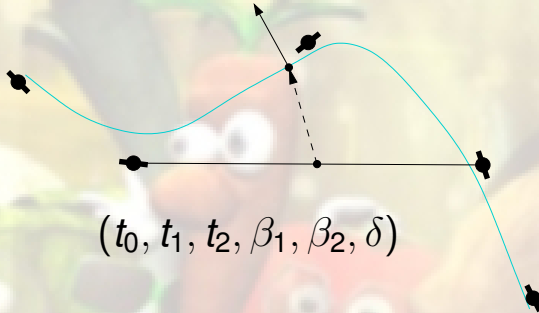
- 1 Compute base position
- 2 Estimate normal direction at base position
- 3 Intersect ray with surface
(simplification of [Adamson-Alexa 04])

Synthesis Procedure



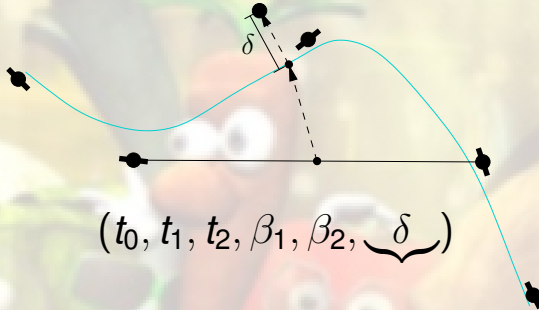
- 1 Compute base position
- 2 Estimate normal direction at base position
- 3 Intersect ray with surface
(fast estimation with $\tilde{\delta}$)

Synthesis Procedure



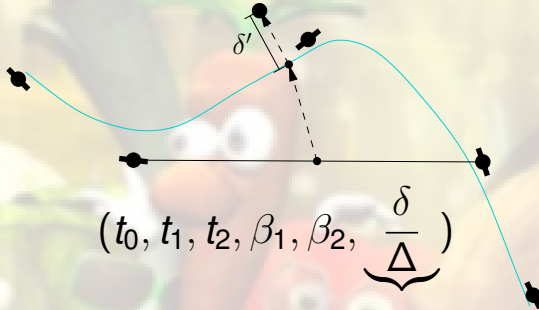
- 1 Compute base position
- 2 Estimate normal direction at base position
- 3 Intersect ray with surface
- 4 Estimate normal direction at intersection

Synthesis Procedure



- 2 Estimate normal direction at base position
- 3 Intersect ray with surface
- 4 Estimate normal direction at intersection
- 5 Displace by δ

Synthesis Procedure



- 2 Estimate normal direction at base position
- 3 Intersect ray with surface
- 4 Estimate normal direction at intersection
- 5 Displace by $\delta' = \frac{\delta}{\Delta} \Delta'$ [Boubekeur+ 07]

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Igea



134345



43636



14503



4551



1512



500

Armadillo



172974



48312



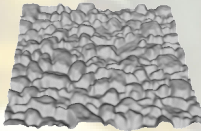
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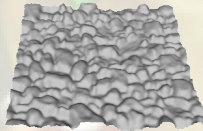
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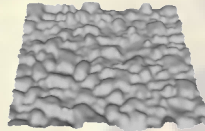
Bumps



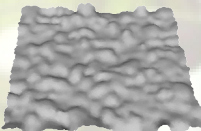
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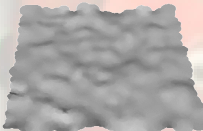
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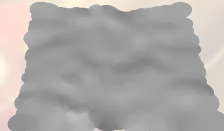
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3583



1140



374

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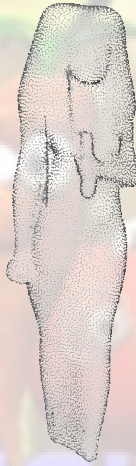
Isis



196256



53883



14953



4368



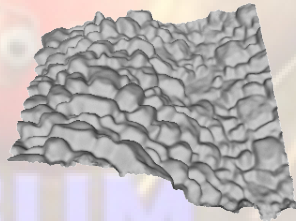
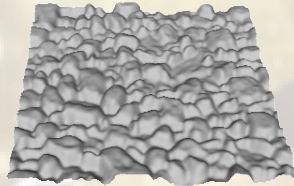
1600

Statistics

	Analysis	Synthesis	RMS error
Igea	27.4 / 60.1	7.6 / 12.2	2.64×10^{-4}
Armadillo	137.4 / —	9.5 / —	9.5×10^{-5}
Bumps	17.9 / 36.7	5.0 / 6.1	4.90×10^{-4}
Isis	39.9 / 67.3	10.5 / 14.4	1.75×10^{-4}

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Deformation



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Detail Emphasis



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Conclusion

- Point-set surfaces are flexible with simple data structures
- No connectivity information can be a pain
- Multiresolution point-set surfaces
 - Verify special conditions when downsampling
 - Detail information with partial topology information

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Conclusion

- Point-set surfaces are flexible with simple data structures
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- Multiresolution point-set surfaces
 - Verify special conditions when downsampling
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- Faster processing for editing (coarser levels), but synthesis time prevents full interactivity.

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Conclusion

- Point-set surfaces are flexible with simple data structures
 - No connectivity information can be a pain
 - Multiresolution point-set surfaces
 - Verify special conditions when downsampling
 - Detail information with partial topology information
 - Faster processing for editing (coarser levels), but synthesis time prevents full interactivity.
- But...

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Future Work

- ... there is hope:
 - Adaptive multiresolution [Zorin+ 97]
 - Highly parallelizable operations (multi-core CPUs, GPU)
- Room for improvement of heuristics' robustness
- Compression

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Future Work

- ... there is hope:
 - Adaptive multiresolution [Zorin+ 97]
 - Highly parallelizable operations (multi-core CPUs, GPU)
- Room for improvement of heuristics' robustness
- Compression
- Wavelets?

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Acknowledgements

- Di Jiang
- This work was supported in parts by grants from NSERC, FQRNT, and MITACS.

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